

Generalize product $A\vec{x}$:

if column vectors of $n \times m$ matrix A are $\vec{v}_1, \dots, \vec{v}_m$
and $\vec{x}$ is a vector in $\mathbb{R}^m$ with components $x_1, \dots, x_m$

$$\text{then } A\vec{x} = \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_m \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} = x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_m \vec{v}_m$$

$$\begin{aligned} \text{ex. } A\vec{x} &= \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} 2 \\ -4 \\ 2 \end{bmatrix} \stackrel{\text{using defn above}}{=} 2 \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix} - 4 \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix} \\ &= \begin{bmatrix} 2 \\ 8 \\ 14 \end{bmatrix} - \begin{bmatrix} 8 \\ 20 \\ 32 \end{bmatrix} + \begin{bmatrix} 6 \\ 12 \\ 18 \end{bmatrix} \\ &= \begin{bmatrix} 2 & -8 & +6 \\ 8 & -20 & +12 \\ 14 & -32 & +18 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

result: zero vector

Linear Combinations

a vector $\vec{b}$ in $\mathbb{R}^n$ is a linear combination of vectors $\vec{v}_1, \dots, \vec{v}_m$ in $\mathbb{R}^n$

if there exists scalars $x_1, \dots, x_m$ s.t.

$$\vec{b} = x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_m \vec{v}_m$$

e. is $\vec{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ a linear combination of $\vec{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ and $\vec{w} = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$?

setup:

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = x \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + y \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

goal: find scalars x, y that will make system consistent

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ 2x \\ 3x \end{bmatrix} + \begin{bmatrix} 4y \\ 5y \\ 6y \end{bmatrix}$$

↓ can also be written as the system:

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$$\begin{cases} x + 4y = 1 \\ 2x + 5y = 1 \\ 3x + 6y = 1 \end{cases}$$

reduce $M = \begin{bmatrix} 1 & 4 & 1 \\ 2 & 5 & 1 \\ 3 & 6 & 1 \end{bmatrix} \xrightarrow{\text{ref}(M)} \begin{bmatrix} x & y & \\ 1 & 0 & -\frac{1}{3} \\ 0 & 1 & \frac{1}{3} \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{matrix} x = -\frac{1}{3} \\ y = \frac{1}{3} \end{matrix}$

conclusion: system is consistent when $x = -\frac{1}{3}$ and $y = \frac{1}{3}$

$\vec{b}$ is a linear combination of $\vec{v}$ and $\vec{w}$ when
 $\vec{b} = -\frac{1}{3}\vec{v} + \frac{1}{3}\vec{w}$

Algebraic Rules for $A\vec{x}$:

if • A is an $n \times m$ matrix
• $\vec{x}, \vec{y}$ are vectors in $\mathbb{R}^m$
• k is a scalar

then $A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y}$
and
 $A(k\vec{x}) = k \cdot A\vec{x}$

ex. consider system $\begin{cases} 3x_1 + x_2 = 7 \\ x_1 + 2x_2 = 4 \end{cases}$

↓ think of this geometrically ...

$3x + y = 7$ and $x + 2y = 4$
also $(y = -3x + 7)$ $(y = -\frac{1}{2}x + 2)$

note: intersection of 2 lines or
solution of system is $(2, 1)$

write as an augmented matrix:

$$A = \left[\begin{array}{cc|c} 3 & 1 & 7 \\ 1 & 2 & 4 \end{array} \right] \longrightarrow \text{ref}(A) = \left[\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 1 \end{array} \right]$$

↑ same (ofc)

alternatively, write system in vector form:

$$\begin{bmatrix} 3x_1 + x_2 \\ x_1 + 2x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$$

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$$\begin{bmatrix} 3x_1 \\ x_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ 2x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 1 \end{bmatrix} x_1 + \begin{bmatrix} 1 \\ 2 \end{bmatrix} x_2 = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$$

conclusion: solving system amounts to writing $\begin{bmatrix} 7 \\ 4 \end{bmatrix}$ as a linear combination of vectors $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

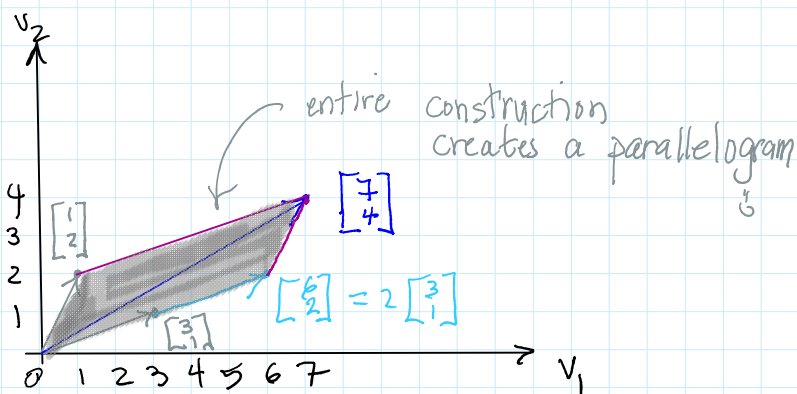
plotting vectors

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

ex. plot $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

ex plot $\begin{bmatrix} 7 \\ 4 \end{bmatrix}$

vectors have direction and magnitude



know this system works when $x_1 = 2$ and $x_2 = 1$:

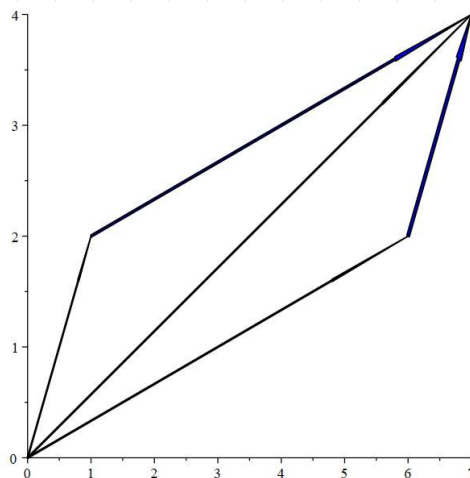
$$\begin{bmatrix} 3 \\ 1 \end{bmatrix} 2 + \begin{bmatrix} 1 \\ 2 \end{bmatrix} 1 = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \leftarrow \text{scalars (components)}$$

solution set of LC

then $\begin{bmatrix} 6 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$

$$\begin{bmatrix} 6+1 \\ 2+2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$$



Section 2-1 Linear Transformations

ex. encoding a position

actual position (measured w Eastern longitude and Northern longitude)

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$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

encoded position: $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ where $y_1 = x_1 + 3x_2$
 $y_2 = 2x_1 + 5x_2$ ↖ get A

then coding can be written as a transformation:

$$\vec{y} = A \vec{x}$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

if actual position is $\vec{x} = \begin{bmatrix} 5 \\ 42 \end{bmatrix}$ then encoded position is

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} 5 \\ 42 \end{bmatrix}$$

$$= 5 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 42 \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

$$= \begin{bmatrix} 5 + 42(3) \\ 5(2) + 42(5) \end{bmatrix} = \begin{bmatrix} 131 \\ 220 \end{bmatrix}$$

↑ $\vec{y}$ (encoded position)

if given $\vec{y} = \begin{bmatrix} 133 \\ 223 \end{bmatrix}$, find actual position, $\vec{x}$

set up: $\begin{bmatrix} 133 \\ 223 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$
↖ $\vec{x}$

to solve for $\vec{x}$ (in general)

$$\begin{array}{l} \text{I} \left| \begin{array}{cc|cc} x_1 & +3x_2 & = & y_1 \\ 2x_1 & +5x_2 & = & y_2 \end{array} \right| \begin{array}{l} \xrightarrow{*2} \\ \xrightarrow{-2} \end{array} \begin{array}{cccc} x_1 & x_2 & y_1 & y_2 \\ -2 & -6 & -2 & \\ 2 & 5 & & 1 \\ \hline 0 & -1 & -2 & 1 \end{array} \\ \downarrow \\ \text{I} \left| \begin{array}{cc|cc} x_1 & +3x_2 & = & y_1 \\ & x_2 & = & 2y_1 - y_2 \end{array} \right| \begin{array}{l} \xrightarrow{*1} \\ \xrightarrow{-1} \end{array} \begin{array}{cccc} & x_2 & y_1 & y_2 \\ & 0 & 1 & 2 & -1 \\ 1 & 3 & 1 & 0 \\ & -3 & -6 & +3 \\ \hline 1 & 0 & -5 & 3 \end{array} \\ \downarrow \\ \left| \begin{array}{cc|cc} x_1 & & = & -5y_1 + 3y_2 \\ & x_2 & = & 2y_1 - y_2 \end{array} \right| \end{array}$$

$$\left| \begin{array}{l} x_1 \\ x_2 \end{array} \right| = \begin{array}{l} -5y_1 + 3y_2 \\ 2y_1 - y_2 \end{array} \quad \begin{array}{c} \hline 1 \quad 0 \quad -5 \quad 3 \\ \hline \end{array}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -5 & 3 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$\vec{x} = B \vec{y}$$

then matrix B is the inverse of matrix A
or $B = A^{-1}$